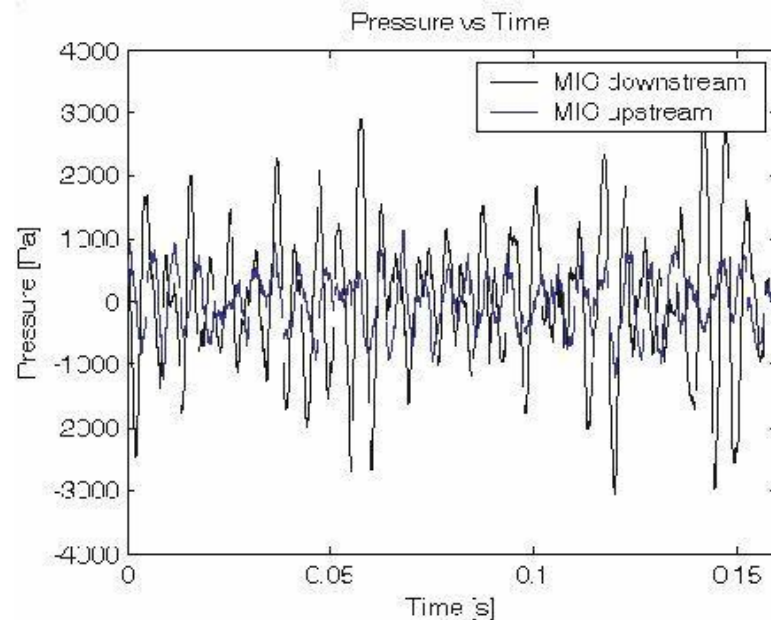


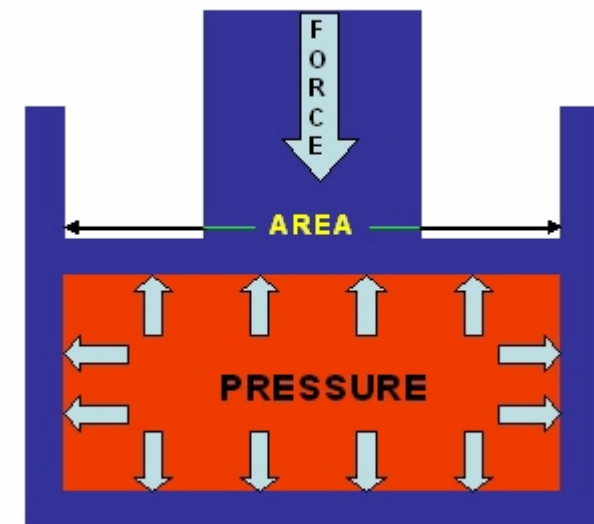
Introduction

Pressure measurement may be divided into two groups:

- The measurement of a static pressure.
- The measurement of a fluctuating pressure



$$\text{PRESSURE} = \frac{\text{FORCE}}{\text{AREA}}$$

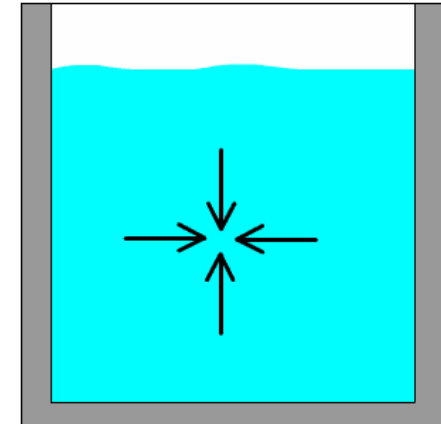


Force acts perpendicular to the enclosing area

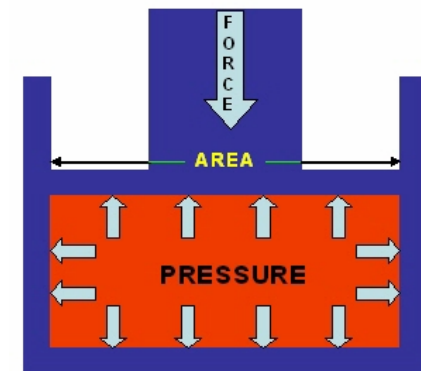


Principles of Pressure Measuring Devices

1. The pressure is strongly influenced by position within a static fluid, but at a given position it is quite independent of direction (principle being employed in manometers).
2. Pressure is unaffected by the shape of the confining boundaries therefore a great variety of fluid pressure transducers is available.
3. Pressure applied to a confined fluid through a movable surface is transferred undiminished throughout the fluid to a bounding surface; a principle employed in dead-weight testers.



$$\text{PRESSURE} = \frac{\text{FORCE}}{\text{AREA}}$$

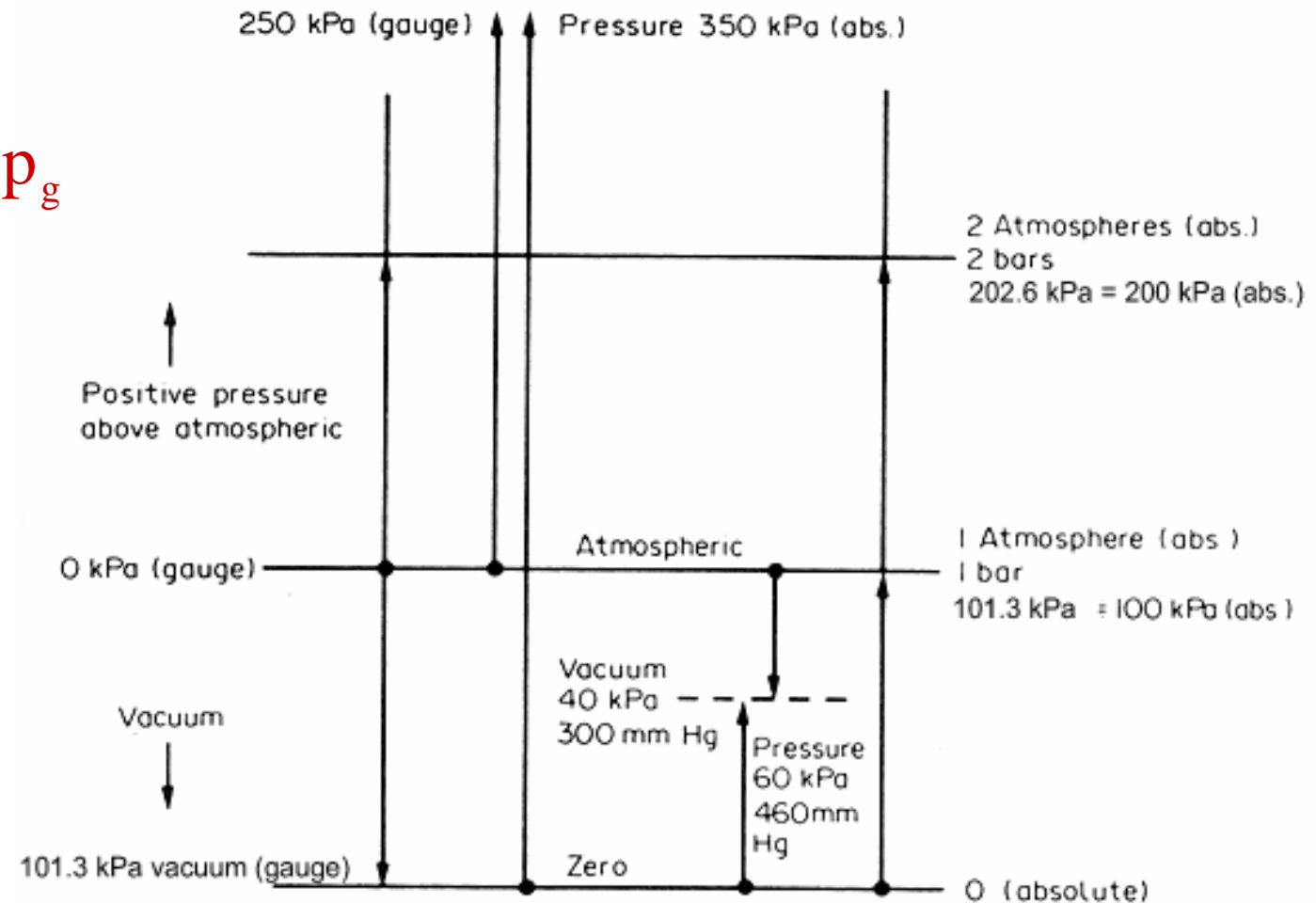


Force acts perpendicular to the enclosing area



Static Pressure Measurement

$$p_{\text{abs}} = p_{\text{atm}} + p_g$$



Differential Pressure Measurement

Devices for differential pressure measurement

1. Manometers

- Simple U-tube manometer
- Industrial U-tube manometer
- The Cistern manometer
- The two-liquid U-tube manometer
- The inclined manometer

2. The ring balance

3. Diaphragms & bellows
Gauges

- Single diaphragm
- Diaphragm stack
- Metallic capsule
- Metallic bellows



The Simple U-Tube Manometer

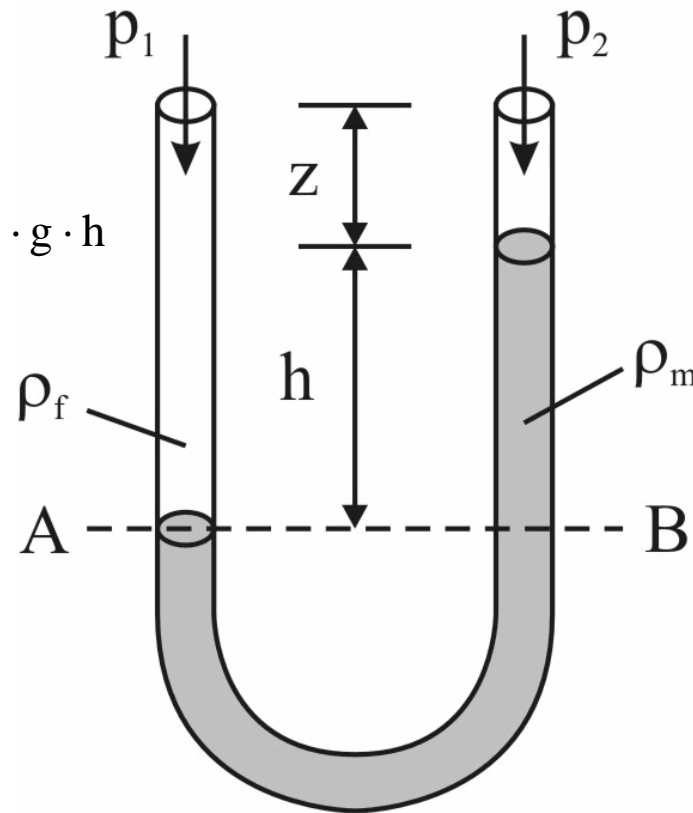
$$p_A = p_B$$

$$p_1 + \rho_f \cdot g \cdot (z + h) = p_2 + \rho_f \cdot g \cdot z + \rho_m \cdot g \cdot h$$

$$p_1 - p_2 = \rho_m \cdot g \cdot h - \rho_f \cdot g \cdot h$$

$$p_1 - p_2 = \Delta p = \rho_m \cdot g \cdot h$$

$$\sigma_{u-Tube} = \frac{dh}{d\Delta p} = \frac{1}{\rho_m \cdot g}$$



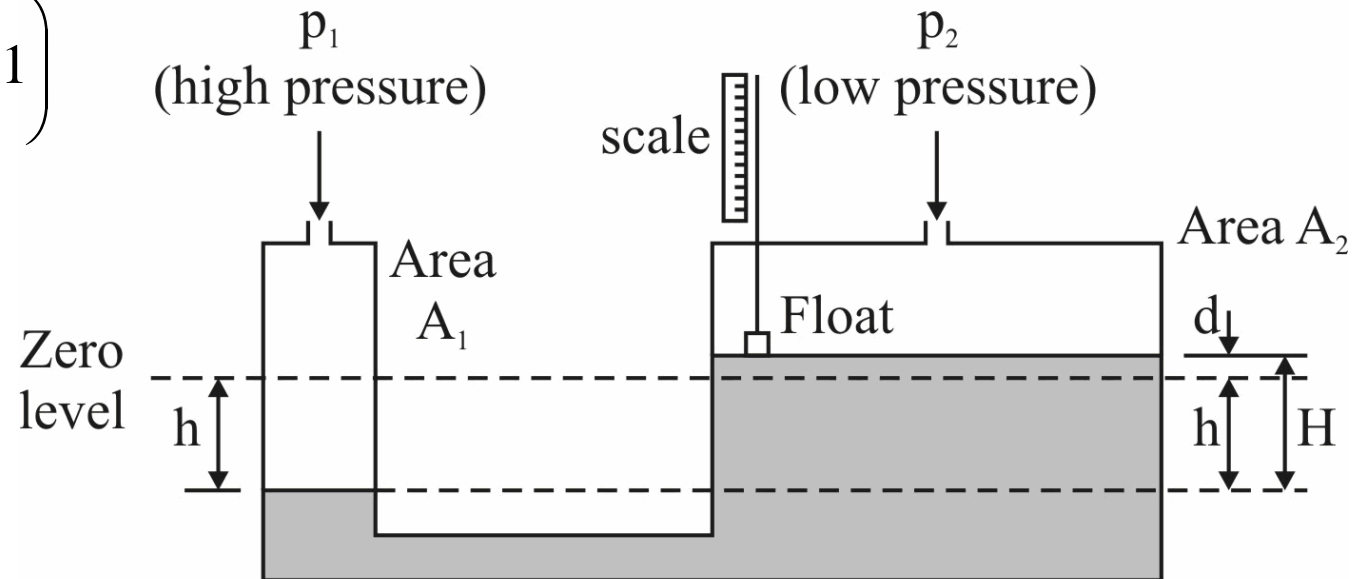
The Industrial U-Tube Manometer

$$p_1 = p_2 + \rho g H = p_2 + \rho g (h + d)$$

$$A_1 \cdot h = A_2 \cdot d \longrightarrow h = \frac{A_2}{A_1} \cdot d$$

$$p_1 - p_2 = \rho g d \left(\frac{A_2}{A_1} + 1 \right)$$

$$d = \frac{(p_1 - p_2)}{[\rho g (A_2/A_1 + 1)]}$$



The Cistern Manometer

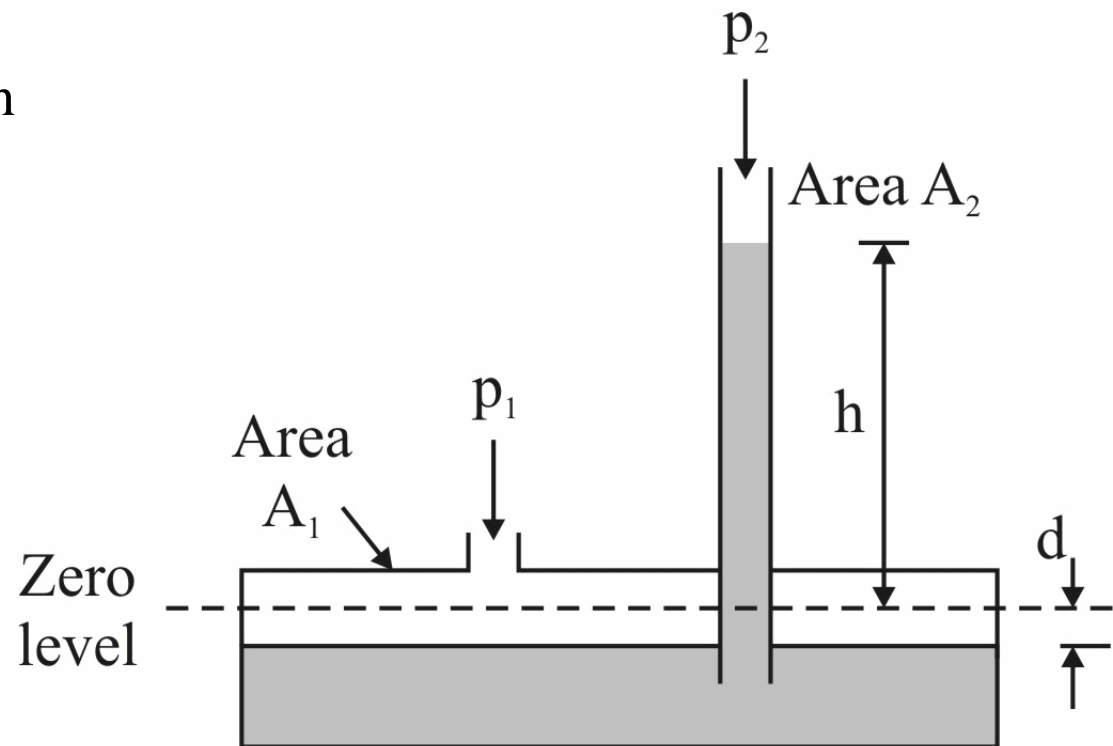
$$p_1 - p_2 = \rho g (h + d)$$

$$A_1 \cdot d = A_2 \cdot h \longrightarrow d = \frac{A_2}{A_1} \cdot h$$

$$p_1 - p_2 = \rho g h \left(1 + \frac{A_2}{A_1} \right)$$

If the value of A_2/A_1 is so small that it may be neglected then

$$p_1 - p_2 = \rho g h$$



The Inclined Tube Manometer

$$p_1 - p_2 = \rho g (h_1 + h)$$

$$h = d \sin \alpha$$

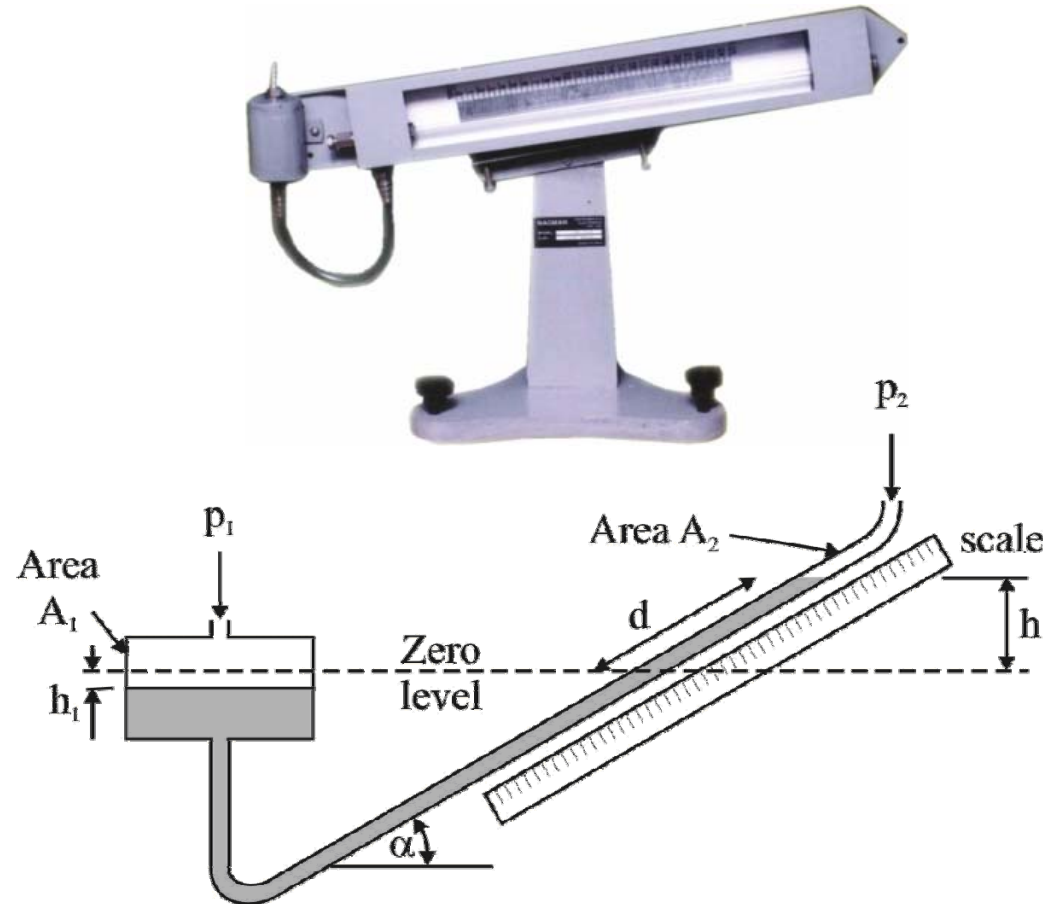
$$h_1 = \frac{A_2}{A_1} \cdot d$$

$$p_1 - p_2 = \rho g d \left(\frac{A_2}{A_1} + \sin \alpha \right)$$

If A_1 is large compared with A_2

$$p_1 - p_2 = \rho g d \cdot \sin \alpha = \rho g h$$

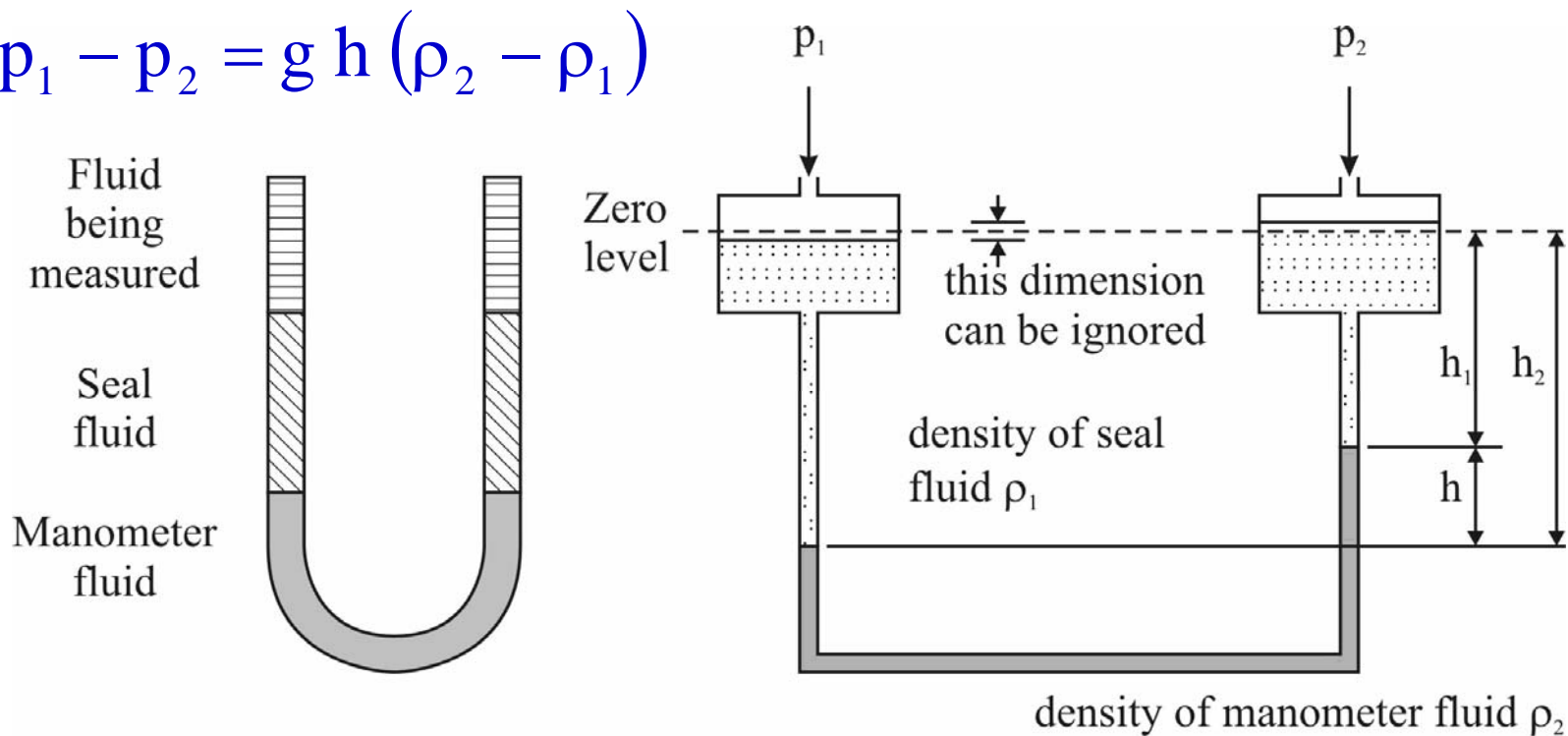
$$S_{\text{inc. man.}} = \Delta \text{output} / \Delta \text{input} = d(d) / d(p_1 - p_2) = 1 / (\rho g \cdot \sin \alpha)$$



The Two Liquid U-Tube Manometer

It may be necessary to separate the liquid from the manometer liquid by using a sealing fluid. For example, if the two liquids react when mixed so seal fluid is required.

$$p_1 - p_2 = g h (\rho_2 - \rho_1)$$



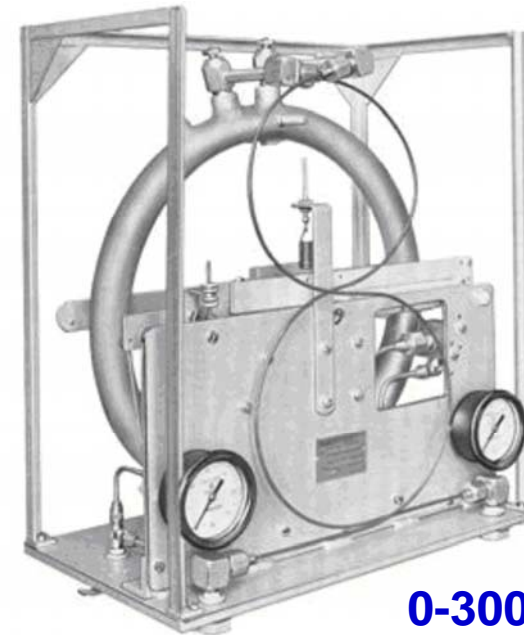
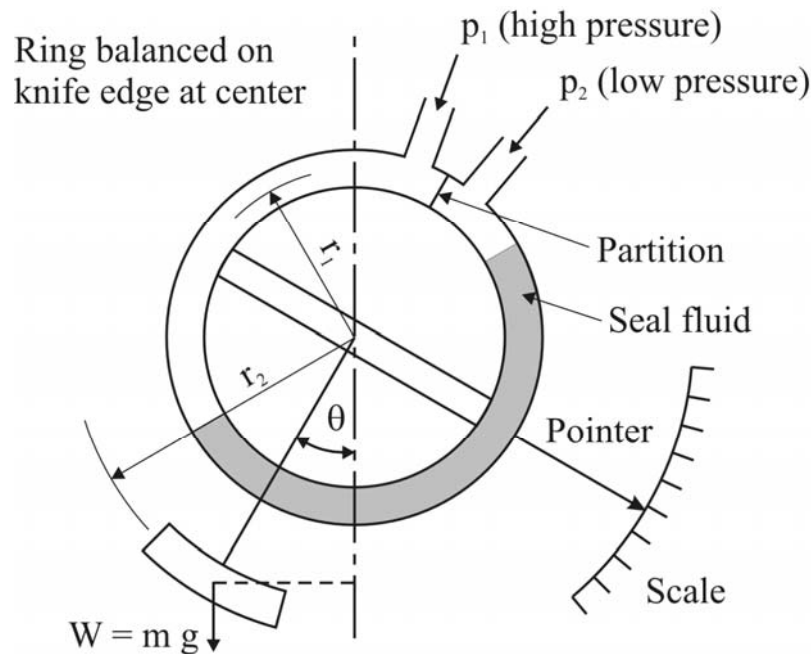
The Ring Balance

It is usually employed for low differential pressure.

$$\text{Rotating moment} = (p_1 - p_2) \cdot A \cdot r_1$$

$$\text{Restoring moment} = (m g) \cdot r_2 \cdot \sin \theta$$

$$p_1 - p_2 = \frac{m g \cdot r_2}{A \cdot r_1} \cdot \sin \theta$$



0-300 mm water



